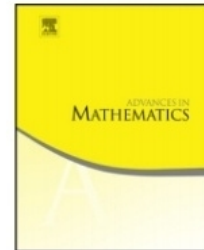




Contents lists available at ScienceDirect

Advances in Mathematics

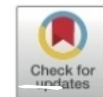
www.elsevier.com/locate/aim



Zero-entropy dynamical systems with the gluing orbit property

Peng Sun

China Economics and Management Academy, Central University of Finance and Economics, Beijing 100081, China



ARTICLE INFO

Article history:

Received 26 May 2019
Received in revised form 1 March 2020
Accepted 25 June 2020
Available online xxxx
Communicated by Vadim Kaloshin

MSC:

primary 37B05, 37B40, 37C50
secondary 37A35, 37C40

Keywords:

Gluing orbit property
Topological entropy
Equicontinuity
Minimality
Uniform rigidity
Intermediate entropy

ABSTRACT

Under the assumption of the gluing orbit property, equivalent conditions to having zero topological entropy are investigated. In particular, we show that a dynamical system has the gluing orbit property and zero topological entropy if and only if it is minimal and equicontinuous.

© 2020 Elsevier Inc. All rights reserved.

Setting:
 X esp. metrisco compacto
 $f: X \rightarrow X$ continua.



ELSEVIER



ScienceDirect

Journal of Differential Equations 272 (2021) 203–221

Journal of
Differential
Equations

www.elsevier.com/locate/jde

Gluing orbit property and partial hyperbolicity

Thiago Bomfim^a, Maria Joana Torres^b, Paulo Varandas^{c,*}

^a Departamento de Matemática, Universidade Federal da Bahia, Av. Ademar de Barros s/n, 40170-110 Salvador, Brazil

^b CMAT and Departamento de Matemática, Universidade do Minho, Campus de Gualtar, 4700-057 Braga, Portugal

^c CMUP and Departamento de Matemática, Universidade Federal da Bahia, Av. Ademar de Barros s/n, 40170-110 Salvador, Brazil

Received 8 May 2020; revised 18 September 2020; accepted 27 September 2020

Available online 2 October 2020

Abstract

This article is a follow up of our recent works [7,8], and here we discuss the relation between the gluing orbit property and partial hyperbolicity. First we prove that a partially hyperbolic diffeomorphism with two saddles with different index, and such that the stable manifold of one of these saddles coincides with the strongly stable leaf does not satisfy the gluing orbit property. In particular, the examples of C^1 -robustly transitive diffeomorphisms introduced by Mañé [20] do not satisfy the gluing orbit property. We also construct some families of partially hyperbolic skew-products satisfying the gluing orbit property and derive some estimates on their quantitative recurrence.

Setting: M variedade C^∞ fechada
com $\dim M \geq 3$
 $f: M \rightarrow M$ difeo C^r , $r \geq 1$.



ELSEVIER



Available online at www.sciencedirect.com

ScienceDirect

J. Differential Equations 267 (2019) 228–266

Journal of
Differential
Equations

www.elsevier.com/locate/jde

GLUING-ORBIT PROPERTY, LOCAL STABLE/UNSTABLE SETS, AND INDUCED DYNAMICS ON HYPERSPACE.

MAYARA ANTUNES, BERNARDO CARVALHO, WELINGTON CORDEIRO, JOSÉ CUETO

ABSTRACT. We prove that local stable/unstable sets of homeomorphisms of an infinite compact metric space satisfying the gluing-orbit property always contain compact and perfect subsets of the space. As a consequence, we prove that if a positively countably expansive homeomorphism satisfies the gluing-orbit property, then the space is a single periodic orbit. We also prove that there are homeomorphisms with gluing-orbit such that its induced homeomorphism on the hyperspace of compact subsets does not have gluing-orbit, contrasting with the case of the shadowing and specification properties, proving that if the induced map has gluing-orbit, then the base map has gluing-orbit and is topologically mixing.

The gluing orbit property, uniform hyperbolicity and large deviations principles for semiflows

Thiago Bomfim *, Paulo Varandas

Departamento de Matemática, Universidade Federal da Bahia, Av. Ademar de Barros s/n, 40170-110 Salvador, Brazil

Received 22 October 2015; revised 8 January 2019

Available online 22 January 2019

Abstract

We introduce a gluing orbit property, weaker than specification, for both continuous maps and flows. We prove that flows with the C^1 -robust gluing orbit property are uniformly hyperbolic and that every uniformly hyperbolic flow satisfies the gluing orbit property. We also prove a level-1 large deviations principle and a level-2 large deviations lower bound for semiflows with the gluing orbit property. As a consequence we establish a level-1 large deviations principle for hyperbolic flows and every continuous observable, and also a level-2 large deviations lower bound. Finally, since many non-uniformly hyperbolic flows can be modeled as suspension flows we also provide criteria for such flows to satisfy uniform and non-uniform versions of the gluing orbit property.

© 2019 Elsevier Inc. All rights reserved.

MSC: 37D20; 37C20; 37C50; 60F10; 37C75

Keywords: Gluing orbit property; Specification; Semiflows; Hyperbolicity; Stability; Large deviations

Propriedade de
gluing orbit

(Introduzida em Bomfim
Varandas, Tenen (2017/2019))

Idéia: Reconstrução
de órbitas

- Mais fraca que a propriedade de especificação.

2.1. The gluing orbit property

Definition 2.1. We call a sequence

$$\mathcal{C} = \{(x_j, m_j)\}_{j \in \mathbb{Z}^+}$$

of ordered pairs in $X \times \mathbb{Z}^+$ an *orbit sequence*. A *gap* for an orbit sequence is a sequence

$$\mathcal{G} = \{t_j\}_{j \in \mathbb{Z}^+}$$

of positive integers. For $\varepsilon > 0$, we say that $(\mathcal{C}, \mathcal{G})$ can be ε -traced by $z \in X$ if the following *tracing property* (illustrated in Fig. 2) holds:

For every $j \in \mathbb{Z}^+$,

$$d(f^{s_j+l}(z), f^l(x_j)) \leq \varepsilon \text{ for each } l = 0, 1, \dots, m_j - 1, \quad (1)$$

where

$$s_1 := 0 \text{ and } s_j := \sum_{i=1}^{j-1} (m_i + t_i - 1) \text{ for } j \geq 2.$$

$$\forall \varepsilon > 0, \exists M = M(\varepsilon)$$

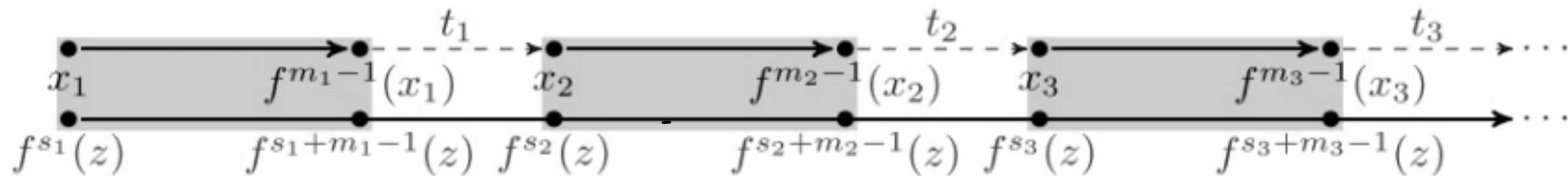
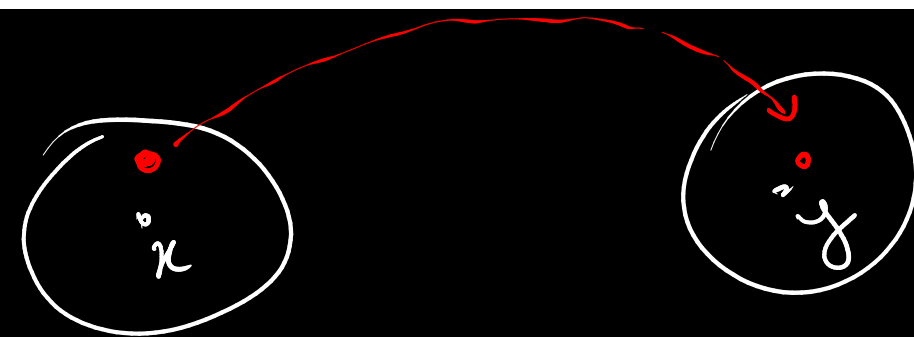


Fig. 2. The tracing property.

Definition 2.2. We say that (X, f) has *the gluing orbit property*, if for every $\varepsilon > 0$ there is $M = M(\varepsilon) > 0$ such that for any orbit sequence \mathcal{C} , there is a gap $\mathcal{G} \in \Sigma_M$ such that $(\mathcal{C}, \mathcal{G})$ can be ε -traced.

são topologicamente transitivos.



Propriedade
de
especificação

Hiperbolicidade
uniforme

Um difeomorfismo C^1 -genérico com propriedade de especificação é um difeomorfismo Anosov transitivo.

Propriedade
de
sombreamento

Hiperbolicidade
uniforme

conjectura

Um dife C^1 -genérico com propriedade de
sombreamento é Axioma A sem ciclos.

Specification-like
properties

Permitted

Comportamentos
não
hiperbólicos

Exemplos de dinâmica satisfazendo a prop.

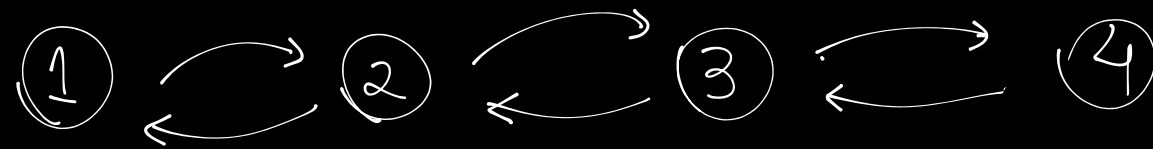
gluing orbit:

- 1 Difeos hiperbólicos transitivos
- 2 Difeos parcialm. hiperbólicos obtidos como tempo 1 de fluxos Anosov [Bonfim, Varanda, 2019]
- 3 Equicontínuos minimais com entropia top. 0.

Ex: Considere a matriz

$$M = \begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 2 & 1 & 0 & 1 & 0 \\ 3 & 0 & 1 & 0 & 1 \\ 4 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Grafo associado à M



Considere o conjunto das sequências admissíveis:

$$\Omega_M = \left\{ (x_k)_{k \in \mathbb{N}} \in \{1, 2, 3, 4\}^{\mathbb{N}} \mid \underbrace{M(x_k, x_{k+1}) = 1} \right\}$$

elemento da linha x_k e coluna x_{k+1} de M .

$$d((x_k), (y_k)) = 2^{-N}, \quad N = \min \{k \mid x_k \neq y_k\}$$

○ shift $\sigma: \Omega_M \rightarrow \Omega_M$ tem gluing orbit.

$$(x_k)_k \mapsto (x_{k+1})_k$$

Obs: σ não tem especificação.

$\forall \epsilon > 0, \exists M = M(\epsilon)$

Gap $\leq M + 2$

Consider $M > 0$; $2^{-M} < \epsilon$

$\underline{x} = (x_k)_k$

$n+M$

$n+M+1$

$\sigma^n(\underline{x})$

y_0

$(y_k)_{k \in \mathbb{N}}$

$x_{n+M} = 1$

$$z_k = \begin{cases} x_k, & k \in \{0, \dots, n+M\} \\ \left. \begin{matrix} 2 \\ 3 \end{matrix} \right\} \leftarrow \\ y_k \end{cases}$$

$z = (z_k) \in \Omega_\epsilon$

$y_0 = 4$

σ \bar{n} tem exp.

$$\epsilon > 0 \quad \text{seja } M = \min \{n \in \mathbb{N} \mid 2^{-n} < \epsilon\}$$

$$M+N$$

M, N pares

$$N > 0$$

$$\underline{x} = (1, 2, 1, 2, \dots)$$

$$\underline{y} = (4, 3, 4, \dots)$$

\exists subsequência x e depois de $N+M$ parnos
subsequência y

$$z_k = \begin{cases} x_k, & k \in \{0, \dots, M\} \\ \vdots \\ y_{k-(N+M)} \end{cases} \quad \begin{array}{l} x_M = 1 \\ \downarrow \text{ímpar} \\ y_0 = 4 \end{array}$$

Enquanto

f com prop.
especifica ca



$$h_{\text{top}}(f) > 0$$

...

f com prop. gluing orbit pode ter

$$h_{\text{top}}(f) = 0$$

Caracterização ...

Artigo Sun

Theorem 1.1. A topological dynamical system has both the *gluing orbit property* and *zero topological entropy* if and only if it is minimal and equicontinuous, i.e. it is topologically conjugate to a minimal rotation on a compact abelian group.

Dado $\varepsilon > 0$
 $\exists \delta > 0$?

$$B(x, \delta) \subset W_{\varepsilon}^{\mu}(x) \cap W_{\varepsilon}^{\nu}(x)$$

} f^{ε}
equicont.

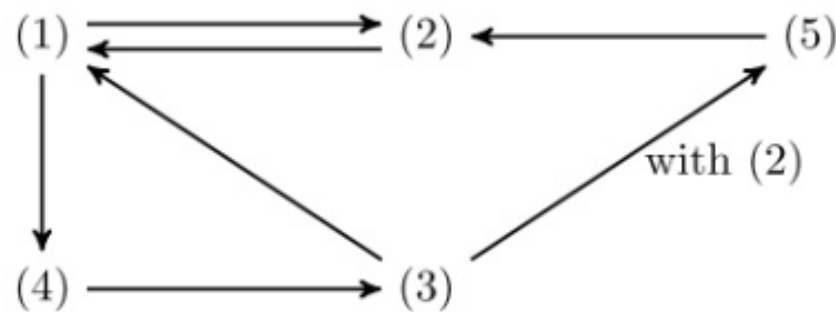


Fig. 1. Conditions in Theorem 1.2.

Theorem 1.2. *Let (X, f) be a system with the gluing orbit property. The following are equivalent:*

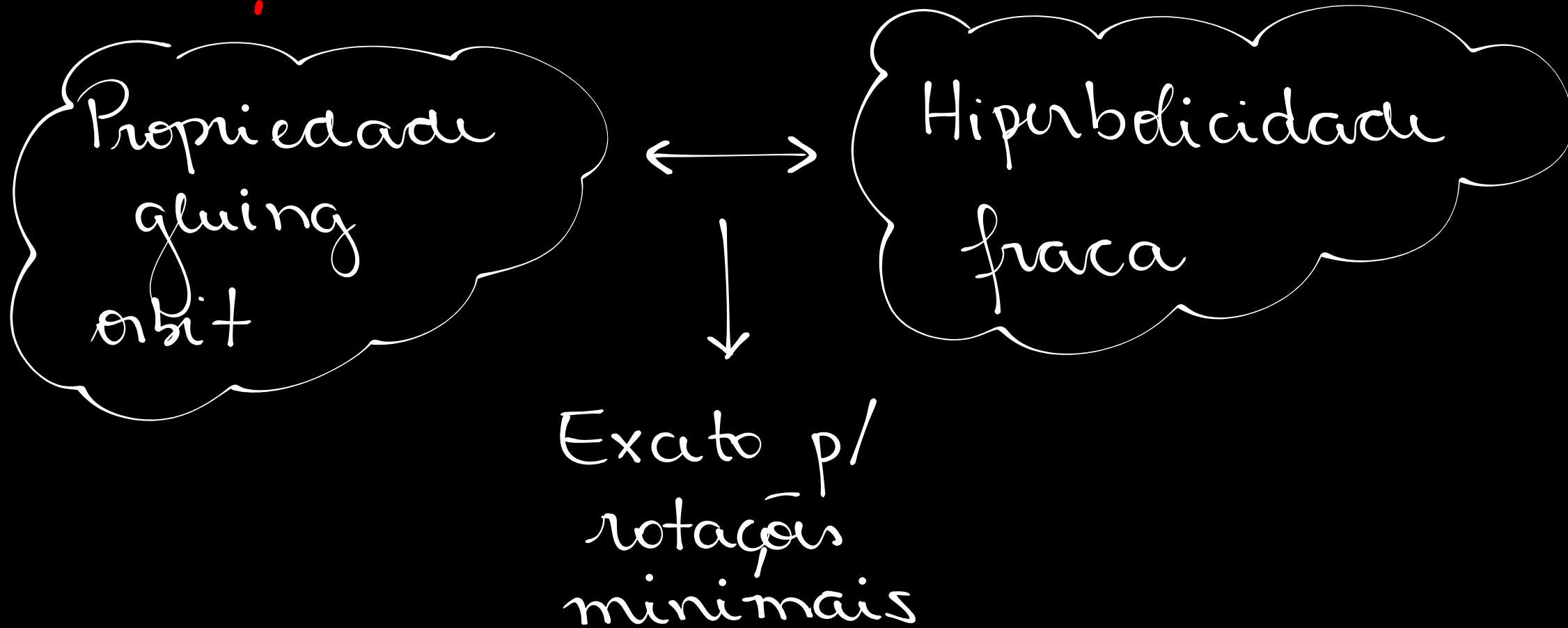
- (1) (X, f) has zero topological entropy.
- (2) (X, f) is minimal.
- (3) (X, f) is equicontinuous.
- (4) (X, f) is uniformly rigid.
- (5) (X, f) is uniquely ergodic.

Quero mostrar que

(1) \Rightarrow (4)

Our proof of the relations between the conditions in Theorem 1.2 is illustrated in Fig. 1. It is well-known that (3) \implies (1) and (2)(3) \implies (5). We have shown in [31] that (1) \implies (2) and (5) \implies (2). We shall prove that (1) \implies (4) in Section 3.2 and (4) \implies (3) in Section 3.3. Finally, we prove that (2) \implies (1) in Section 4.3.

Relação:



Sabemos que:

$h_{\text{top}}(f) > 0 \implies$ expoentes de Lyapunov não-nulos.

Definition 2.9. We say that (X, f) is *equicontinuous* if the family $\{f^n\}_{n=0}^{\infty}$ is equicontinuous, i.e. for every $\varepsilon > 0$, there is $\delta > 0$ such that for any $x, y \in X$ with $d(x, y) < \delta$, we have

$$d(f^n(x), f^n(y)) < \varepsilon \text{ for every } n \in \mathbb{N}.$$

Definition.

We say that (X, f) is *minimal* if $\text{Tran}(X, f) = X$. Equivalently, there is no nonempty proper compact invariant subset of X .

$$\text{Tran}(X, f) := \{x \in X : \overline{O(x)} = X\}$$

Definition 2.16. We say that (X, f) is *uniformly rigid* if there is a sequence $\{n_k\}_{k=1}^{\infty}$ such that

$$\lim_{k \rightarrow \infty} D^0(f^{n_k}, \text{Id}) = 0,$$

i.e. $f^{n_k} \rightarrow \text{Id}$ uniformly.

Uniform rigidity is closely related to recurrence and almost periodicity.

$$[0, 1] \times S^1$$

$$\bar{n} \text{ unif rigid} \Rightarrow h_{\text{top}}(f) > 0$$

Lemma 3.2. *Suppose that (X, f) is not uniformly rigid. Then there is $\gamma > 0$ such that for every $p \in \text{Tran}(X, f)$ and every $m \in \mathbb{Z}^+$, there is $\tau = \tau(p, m) \in \mathbb{N}$ such that*

$$d(f^\tau(p), f^\tau(f^m(p))) > \gamma.$$

$$\exists \gamma > 0 ;$$

$$f^m(p) \notin W_\gamma^\tau(p)$$

Lemma 3.2. Suppose that (X, f) is not uniformly rigid. Then there is $\gamma > 0$ such that for every $p \in \text{Tran}(X, f)$ and every $m \in \mathbb{Z}^+$, there is $\tau = \tau(p, m) \in \mathbb{N}$ such that

$$d(f^\tau(p), f^\tau(f^m(p))) > \gamma.$$

Por absurdo, $\forall \frac{1}{2^k}, \exists p \in \text{Tran}(X, f)$ e $m_k \in \mathbb{N}$;

$$d(f^\tau(p), f^\tau(f^{m_k}(p))) \leq \frac{1}{2^k} \quad \forall \tau$$

Dado $x \in X$. $p \in \text{Tran}(X, f)$.

$$x = \lim_l f^{n_l}(p) \Rightarrow f^{m_k}(x) = f^{m_k}(\lim_l f^{n_l}(p)) = \lim_l f^{m_k}(f^{n_l}(p))$$

$$\Rightarrow d(x, f^{m_k}(x)) \leq \frac{1}{2^k} \Rightarrow \mathcal{D}^0(f^{m_k}, \text{Id}) \leq \frac{1}{2^k} \Rightarrow f^{m_k} \rightarrow \text{Id}. \quad \times$$

Proposition 3.3. *Suppose that (X, f) has the gluing orbit property and it is not uniformly rigid. Then $h(f) > 0$.*

The rest of this subsection is devoted to the proof of Proposition 3.3.

Suppose that (X, f) has the gluing orbit property and it is not uniformly rigid. Let $M := M(\varepsilon)$ be the constant in the gluing orbit property (as in Definition 2.2). By Proposition 2.13, (X, f) is topologically transitive and hence $\text{Tran}(X, f) \neq \emptyset$. By Lemma 3.2, there are $p \in \text{Tran}(X, f)$, $\gamma > 0$ and $0 < \varepsilon < \frac{1}{3}\gamma$ such that for each $k = 1, 2, \dots, 2M - 1$, there is $\tau_k \in \mathbb{N}$ such that

$$d(f^{\tau_k}(p), f^{\tau_k}(f^k(p))) > \gamma. \quad (2)$$

We fix

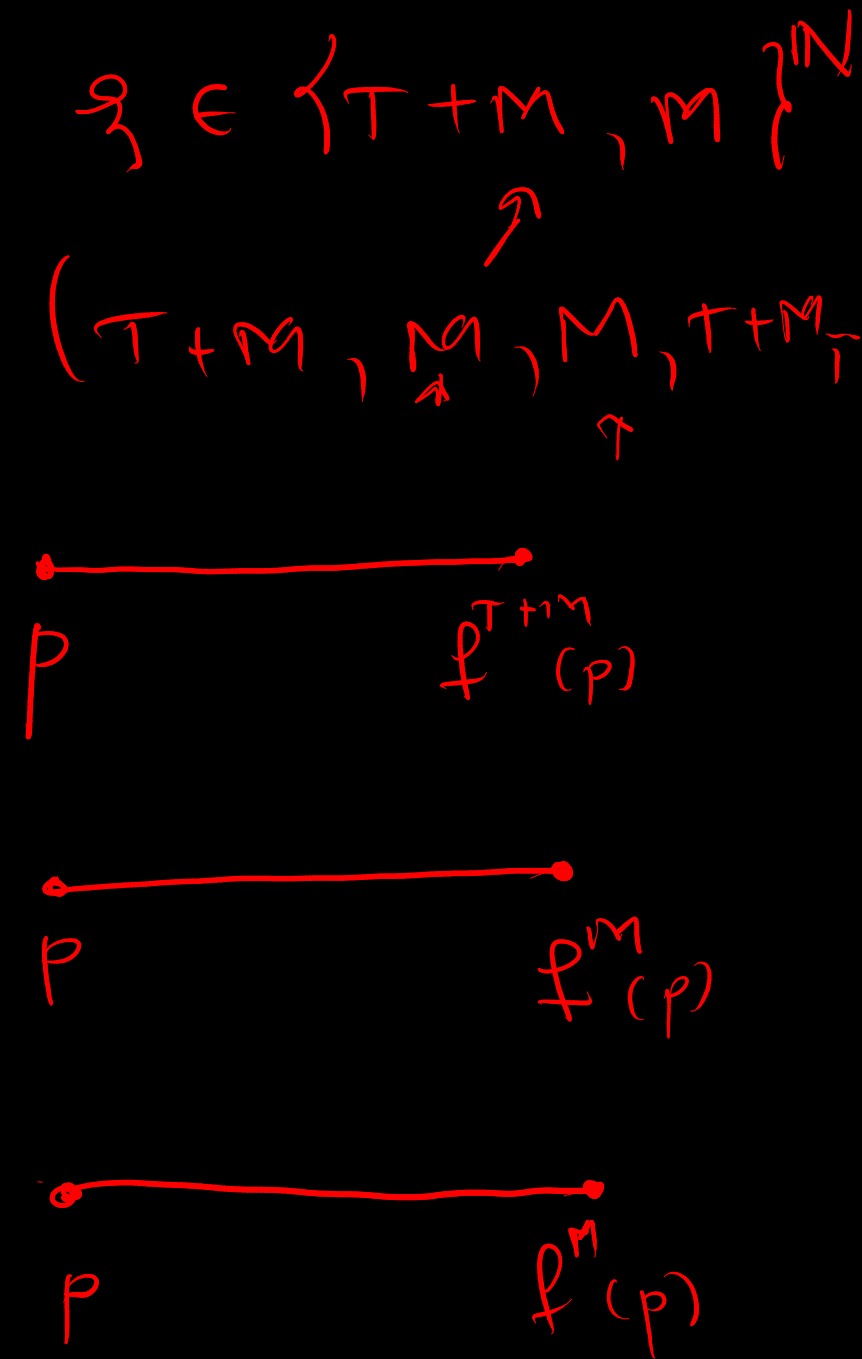
$$T := 2M + \max\{\tau_k : k = 1, \dots, 2M - 1\}. \quad (3)$$

Note that T depends exclusively on p and ε . Denote

$$m_1 := T + M \text{ and } m_2 := T.$$

For each $\xi = \{\xi(k)\}_{k=1}^{\infty} \in \Sigma_2 := \{1, 2\}^{\mathbb{Z}^+}$, denote

$$\mathcal{C}_\xi := \{(p, m_{\xi(k)} + 1)\}_{k=1}^{\infty}.$$



The gluing orbit property ensures that there are $z_\xi \in X$ and

$$\mathcal{G}_\xi = \{t_k(\xi)\}_{k=1}^\infty \in \Sigma_M$$

such that $(\mathcal{C}_\xi, \mathcal{G}_\xi)$ is ε -traced by z_ξ .

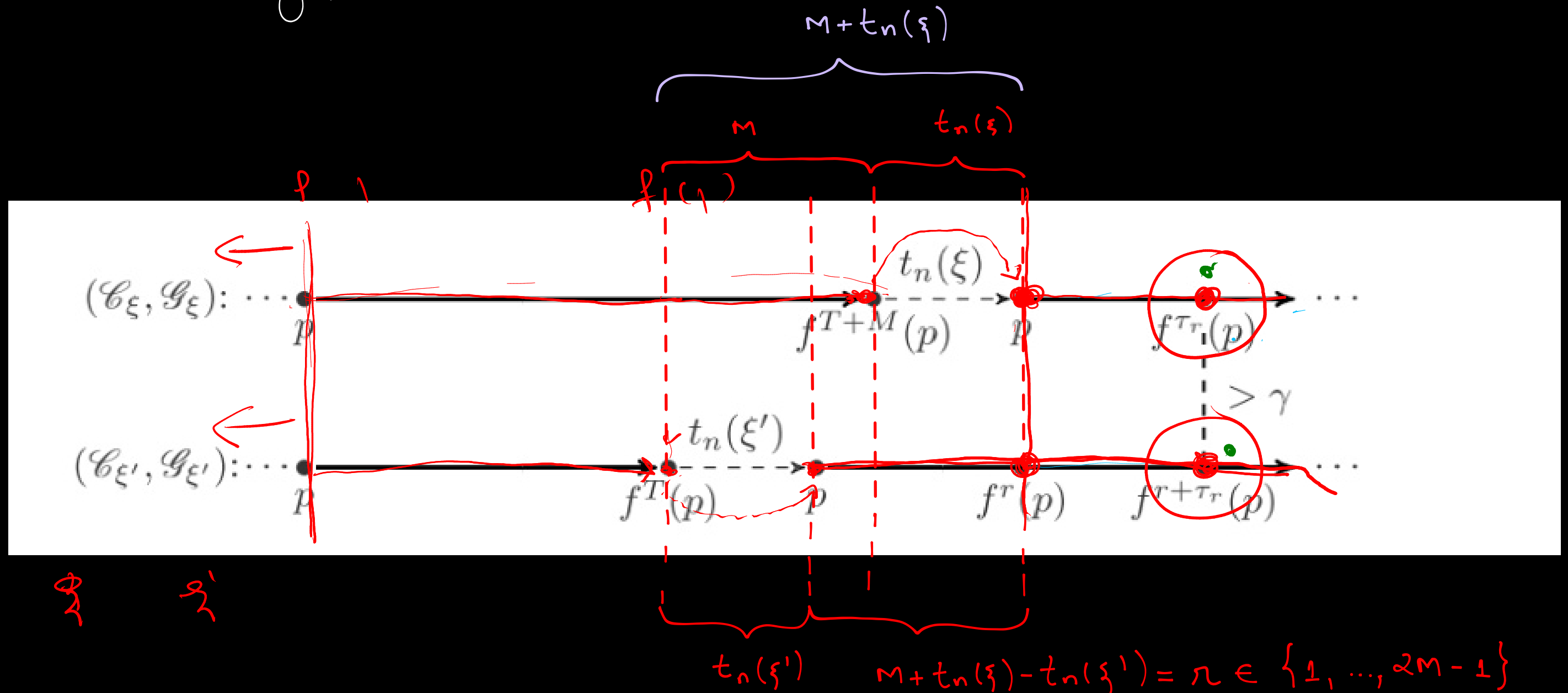
Lemma 3.4. *Let $N \geq 1$. If there is $n \in \{1, \dots, N\}$ such that $\xi(n) \neq \xi'(n)$, then z_ξ and $z_{\xi'}$ are $((N+1)(T+2M), \varepsilon)$ -separated.*

$r(n, \delta)$ denota a maxima cardinalidade de um subconjunto (n, δ) -separado de X .

$$h(f, \delta) = \limsup_{n \rightarrow \infty} \frac{1}{n} \log r_n(f, \delta) \quad h(f) = \lim_{\delta \rightarrow 0} h(f, \delta).$$

$$\geq \limsup \frac{1}{(N+1)(T+2M)} \log 2^N > 0$$

Case 1: Os tamanhos dos pedaços das órbitas de p das seq. se diferem ^{m} antes dos gaps.



caso 2: Os gaps se diferem antes dos pontos de órbitas.

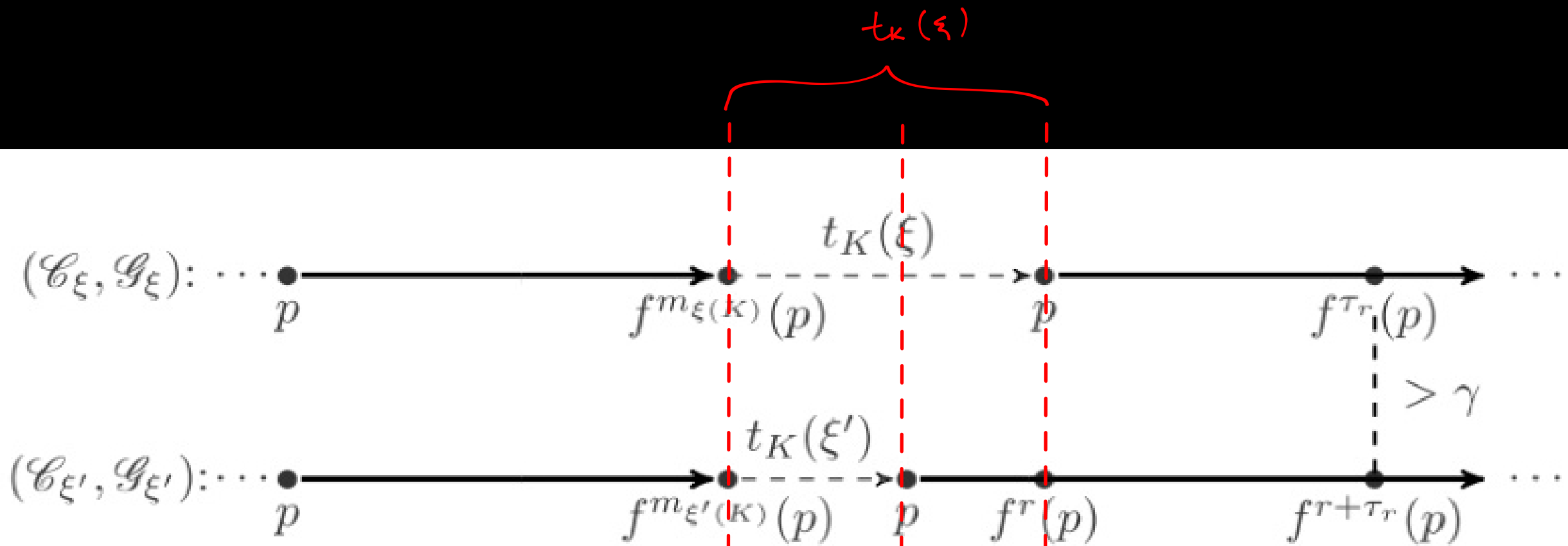


Fig. 4. Separation in Case 2.

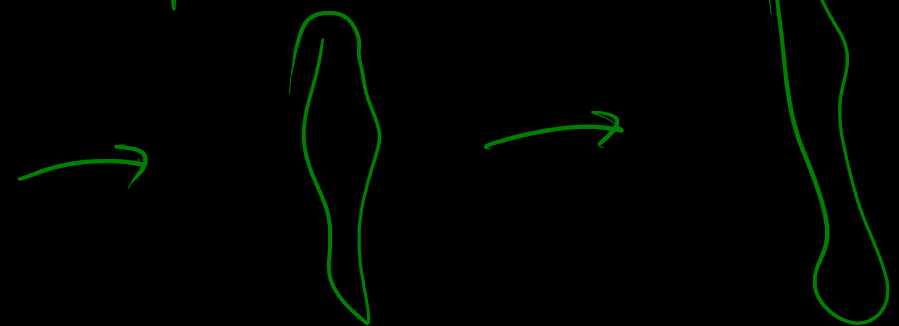
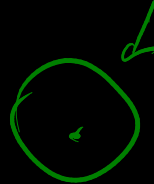
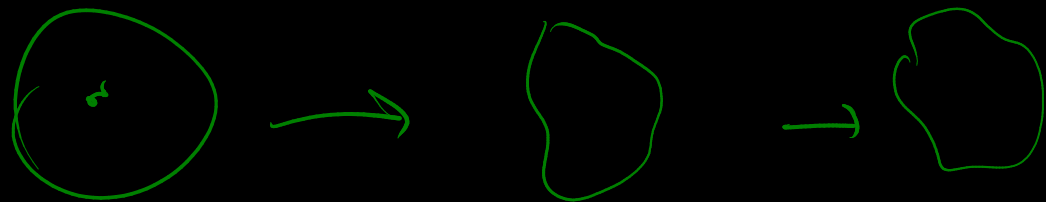
$$t_K(\xi) - t_K(\xi') = \nu \in \{1, \dots, 2M-1\}.$$

Dicotomia

Se $f: X \rightarrow X$ tem propriedade gluing orbit, então f é equicontínuo ou f é sensível.

• $h_{\text{top}}(f) = 0 \iff f$ é equicontínuo

• $h_{\text{top}}(f) > 0 \iff f$ é sensível



$\exists \varepsilon > 0$; $\forall \delta > 0$; dado $x \in X$
 $\exists y \in B(x, \delta) + \eta$
 $d(f^n(x), f^n(y)) > \varepsilon$
para algum $n \in \mathbb{N}$

Prop: Se $f: X \rightarrow X$ é transitivo e não é uniformemente rígido então f é sensível.

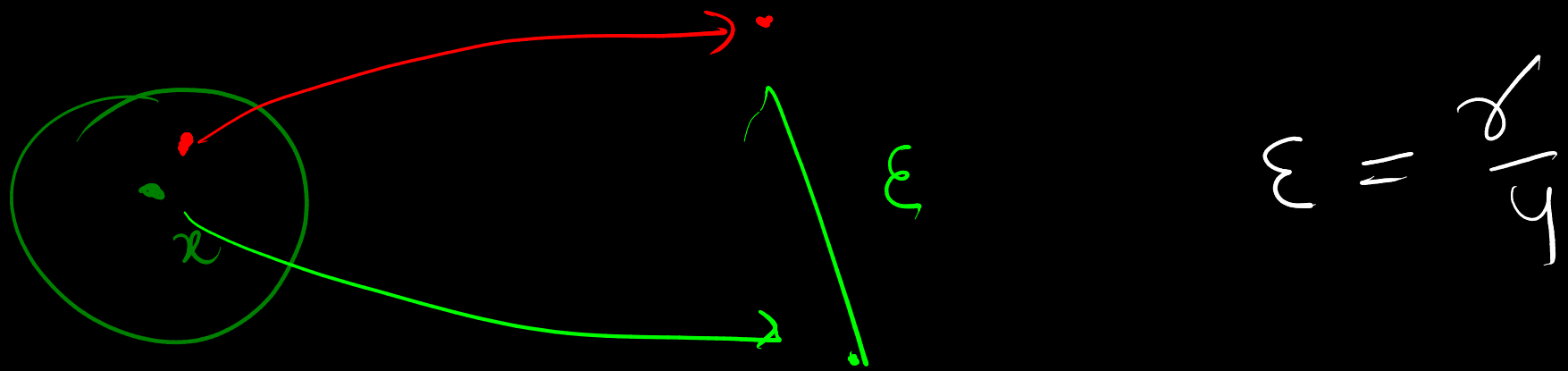
\Downarrow s.o
 $h_{\text{top}}(f) > 0$

Existe $\delta > 0$ do Lema 3.2

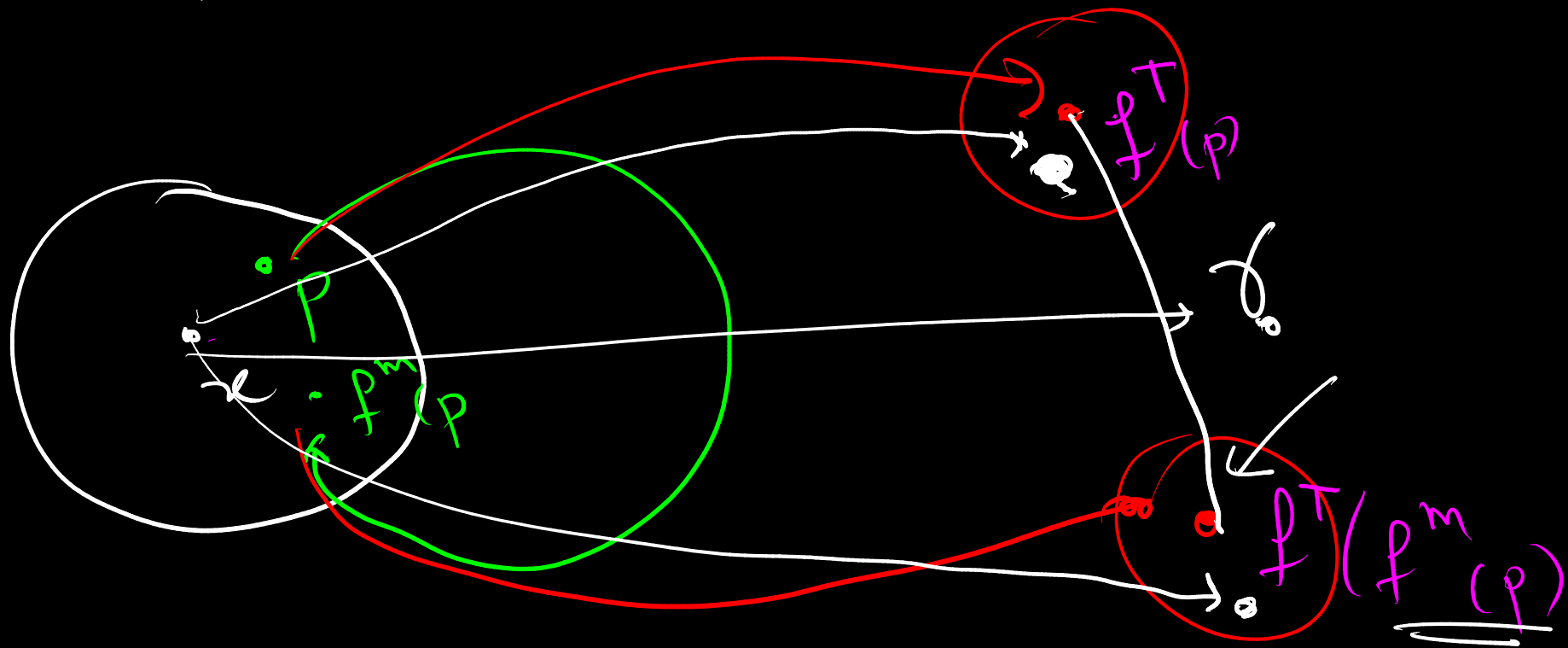
└: $\varepsilon = \frac{\delta}{4}$ é a constante de sensibilidade de f .

Lemma 3.2. Suppose that (X, f) is not uniformly rigid. Then there is $\gamma > 0$ such that for every $p \in \text{Tran}(X, f)$ and every $m \in \mathbb{Z}^+$, there is $\tau = \tau(p, m) \in \mathbb{N}$ such that

$$d(f^\tau(p), f^\tau(f^m(p))) > \gamma. \quad f^m(p) \notin W_\delta^\tau(p) \quad \forall m \in \mathbb{N}.$$



$$p \in \text{Tran}(x, f)$$



Theorem A. If $f: X \rightarrow X$ is a homeomorphism of an infinite compact metric space X satisfying the gluing-orbit property, then there is $\varepsilon_0 > 0$ such that for each $\varepsilon \in (0, \varepsilon_0)$ and each $x \in X$ there are compact and perfect sets

$$C_x \subset W_\varepsilon^s(x) \quad \text{and} \quad D_x \subset W_\varepsilon^u(x).$$

